



LEOPARD
IMAGING

LI-AR0234CS-STEREO-GMSL2-30



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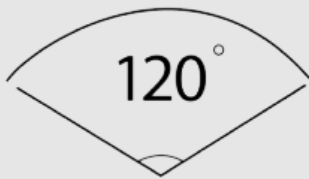
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INTRODUCTION

HAWK, the LI-AR0234CS-STEREO-GMSL2-30 is the professional 3D depth camera where cutting-edge technology meets effortless usability. Equipped with ON Semiconductor 2.3MP CMOS digital image sensor AR0234CS, our HAWK provides unparalleled depth sensing capabilities, allowing ease while teams or enthusiasts work at the edge of ADAS, autonomous driving, robotics and immersive enjoyments. Dive into a world of limitless possibilities with HAWK, where every detail is captured with precision and every interaction is taken to new heights.

FEATURES & HIGHLIGHTS



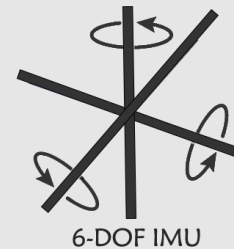
With 121.5° horizontal and 147.5° diagonal field of view, HAWK helps to perceive the world in 3D with greater depth and dimension of field, sharper image quality and more details.



2 x Global shutters capture the entire frame at the same time, freeze the motion at a specific point in time, offering an accurate representation of moving subjects without distortion.



IP65 level resistance to water, dust and humidity ensures remarkable performance for outdoor and indoor applications in different fields like robotics, industrial, medical, agricultural, etc.



Built-in 6-axis IMU for enhanced spatial and positional awareness.



CE and FCC certifications render assurance about safety, protection and product quality.



It is easy to deploy Hawk in different systems and environments thanks to its flat bottom and flexible mounting options.

TECHNICAL SPECIFICATIONS

| General | |
|---|---|
| Use environment | Indoor / Outdoor |
| Baseline | 150 mm |
| IP Rating | IP65 |
| Video Output | 1200P @ 60 fps with output resolution side-by-side 2 × (1920 × 1200) 1200P @ 30 fps with output resolution side-by-side 2 × (1920 × 1200) |
| Power Supply Range | 9 ~ 19 VDC |
| Power Consumption (NVIDIA® AGX Xavier™) | 118 mA @ 12 VDC (2 * 1920 × 1200 @ 60 fps) |
| IMU (Inertial Measurement Unit) | BMI088 |
| Serializer | Maxim GMSL2 |
| Part# | LI-AR0234CS-STEREO-GMSL2-30 |
| MPN (Manufacturer Part Number) | LI-AR0234CS-STEREO-GMSL2-30-V1.0 |
| Depth | |
| Depth Frame Rate | 30 Hz |
| Depth Range | 1.0 ~ 8.0 m NOTE: For high Z-accuracy, the depth range can be 0.5 m to 8.0 m. However, the depth range can be up to 20 m with reduced Z-accuracy. |
| Depth Technology | Neural Stereo Depth Sensing |
| Object Detection | |
| Object Types | Vehicles, persons, custom objects |
| Object Tracking | Supported |
| Detection Outputs | Location, unique ID, bounding boxes 2D, segmentation masks |
| Image Sensor | |
| Sensor | ON Semiconductor 2.3MP CMOS Image Sensor AR0234CS (QTY: 2) |
| Optical Format | 1/2.6" |
| Resolution | 1920 (H) × 1200 (V) (active pixels) |
| Pixel Size | 3.0 × 3.0 μm |
| Output Format | 10-bit RAW |
| Color / Mono | Color |
| Shutter | Global shutter |

LENS SPECIFICATIONS

| | |
|-----------------------|--|
| Focal Length | 2.8 mm |
| Aperture, F/# | 2.0 |
| Field of View (FOV) | 147.5° (diagonal) / 121.5° (horizontal) / 73.5° vertical |
| Optical Distortion | < -65.3% |
| Relative Illumination | > 30% |
| Glass Cover | No |
| IR Filter | 650 nm IR cut filter |
| Lens Mount | Active Alignment (AA) |

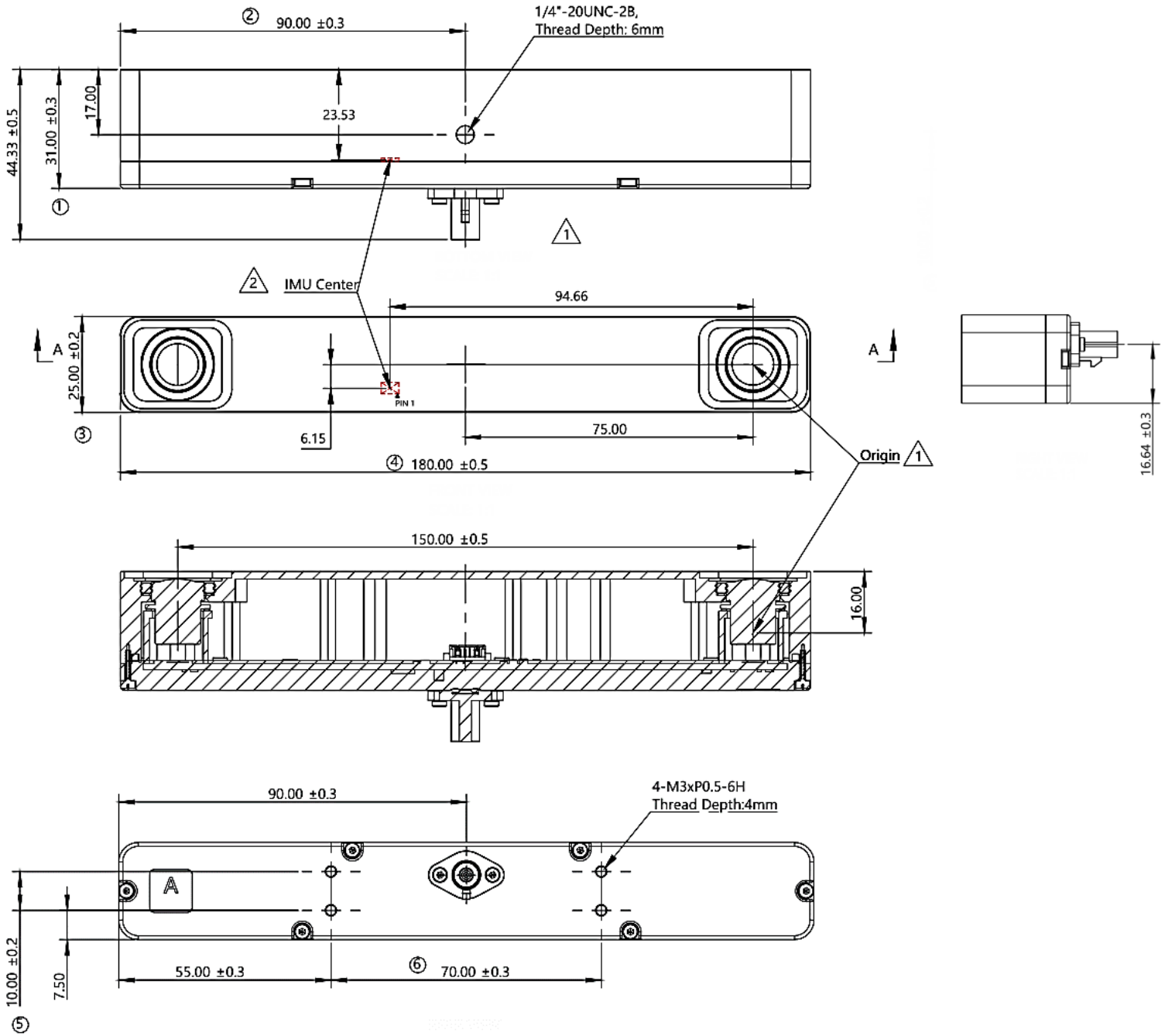
PHYSICAL, ENVIRONMENTAL, & CERTIFICATION

| Physical Features | |
|------------------------|--|
| Weight | ~ 204 g |
| Size | 180.0 (L) × 25.0 (W) × 44.33 (D) mm |
| Connector | Fakra Z type connector |
| Mounting Mechanism | <ul style="list-style-type: none"> • One 1/4"-20 UNC-2B thread mounting point. Thread depth: 6 mm • Four M3 × P0.5-6H thread mounting points. Thread depth: 4 mm • Tripod  |
| Environmental Features | |
| Operating Temp | -20°C ~ +50°C |
| Storage Temp | -40°C ~ +70°C |
| CERTIFICATION | |
| FCC, CE | Yes |

APPLICATIONS

- Bar Code Scanner
- 3D Scanning
- Positional Tracking
- Iris Scanning
- Machine Vision
- Augmented Reality
- Virtual Reality
- Biometrics
- Gesture Recognition
- Depth Sensing

DIMENSIONS



NOTE:

- Other unmarked tolerances are ±0.3 mm.
- ⊗ marked are important sizes.
- △ marked is revision version.
- For unmarked sizes, refer to 3D model.
- All materials are compliant with RoHS requirements.
- IMU location is shown in the drawing.
- Unit: mm

DEPTH PERFORMANCE

SPEC LIMIT (6-Meter Distance)

| Metric | Spec Limit(s) |
|--------------|--|
| Z-Accuracy | $\pm 2\%$ at 6 m distance at 80% depth FOV |
| Z-STD | $\pm 2\%$ at 6 m distance at 80% depth FOV |
| Z-Distortion | $\pm 2\%$ at 6 m distance at 80% depth FOV |
| Z-Fill-Rate | $\pm 0.1\%$ at 6 m distance at 80% depth FOV |

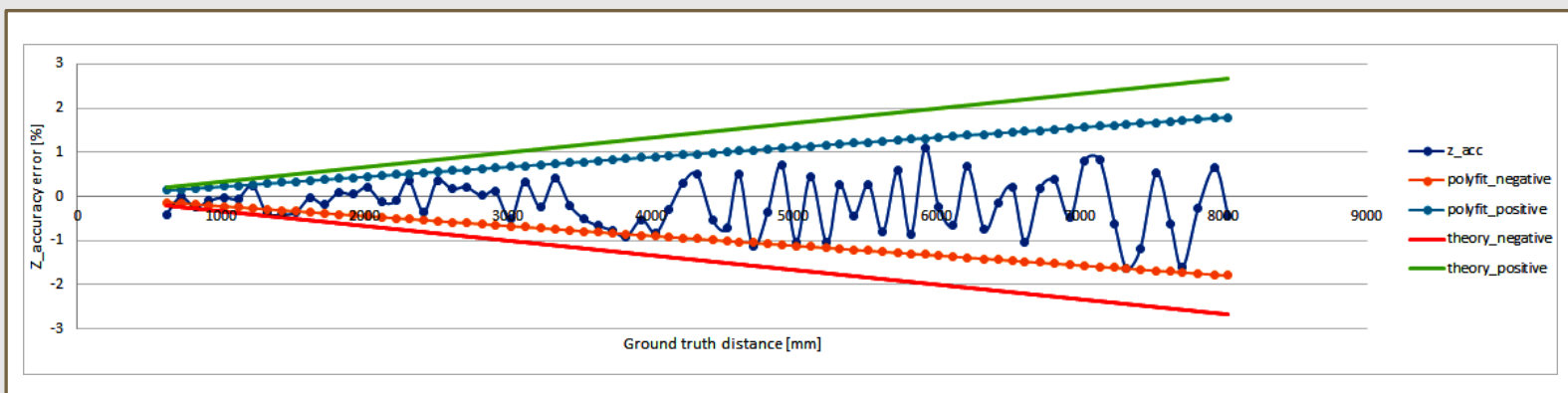
DISTANCE & Z-ACCURACY

NOTE:

Z-STD, Z-DISTORTION, Z-Fill-Rate has little difference for the distance from 1.0 m to 8.0 m.

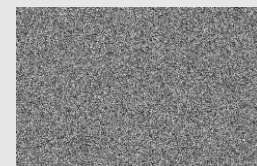
| Distance | Z-Accuracy |
|----------|------------|
| 1 meter | < 0.33% |
| 2 meters | < 0.66% |
| 3 meters | < 0.99% |
| 4 meters | < 1.32% |
| 5 meters | < 1.65% |
| 6 meters | < 2.00% |
| 7 meters | < 2.31% |
| 8 meters | < 2.64% |

MEASURED DATA GRAPH



Test Condition:

1. Target to generate depth image: random_target.bmp (image on the right)
2. The same ROI is selected under all measured distances.
3. ROI size: 100 (W) x 50 (H) pixels



random_target.bmp

● IMAGE ORIENTATION

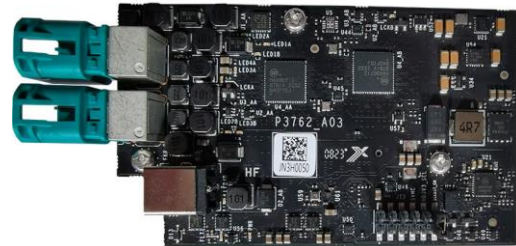


● RECOMMENDED ADAPTER BOARDS

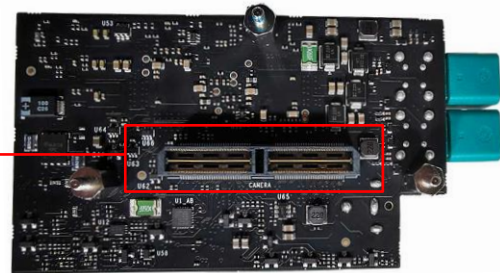
LI-JAG-ADP-GMSL2-8CH:

- Nvidia Part#: P3762_A03
- Supports up to 8 cameras
- DeSerializer: Maxim MAX96712
- Compatible with NVIDIA® Jetson AGX Orin™ Developer Kit and LI-AGO-CB carrier board

For more info, refer to:
<https://leopardimaging.com/product/platform-partners/nvidia/nvidia-jetson-orin/agx-orin-camera-kits/li-jag-adp-gmsl2-8ch/>



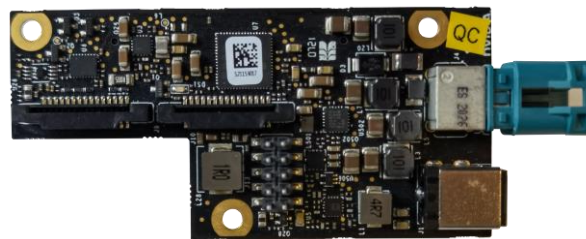
Connector to
 NVIDIA®
 Jetson AGX
 Orin™
 Developer Kit
 or LI-AGO-CB



E3653_A03:

- Supports up to 4 cameras
- DeSerializer: Maxim MAX96712
- Compatible with NVIDIA® Jetson AGX Xavier™ and AGX Orin™ Developer Kit.

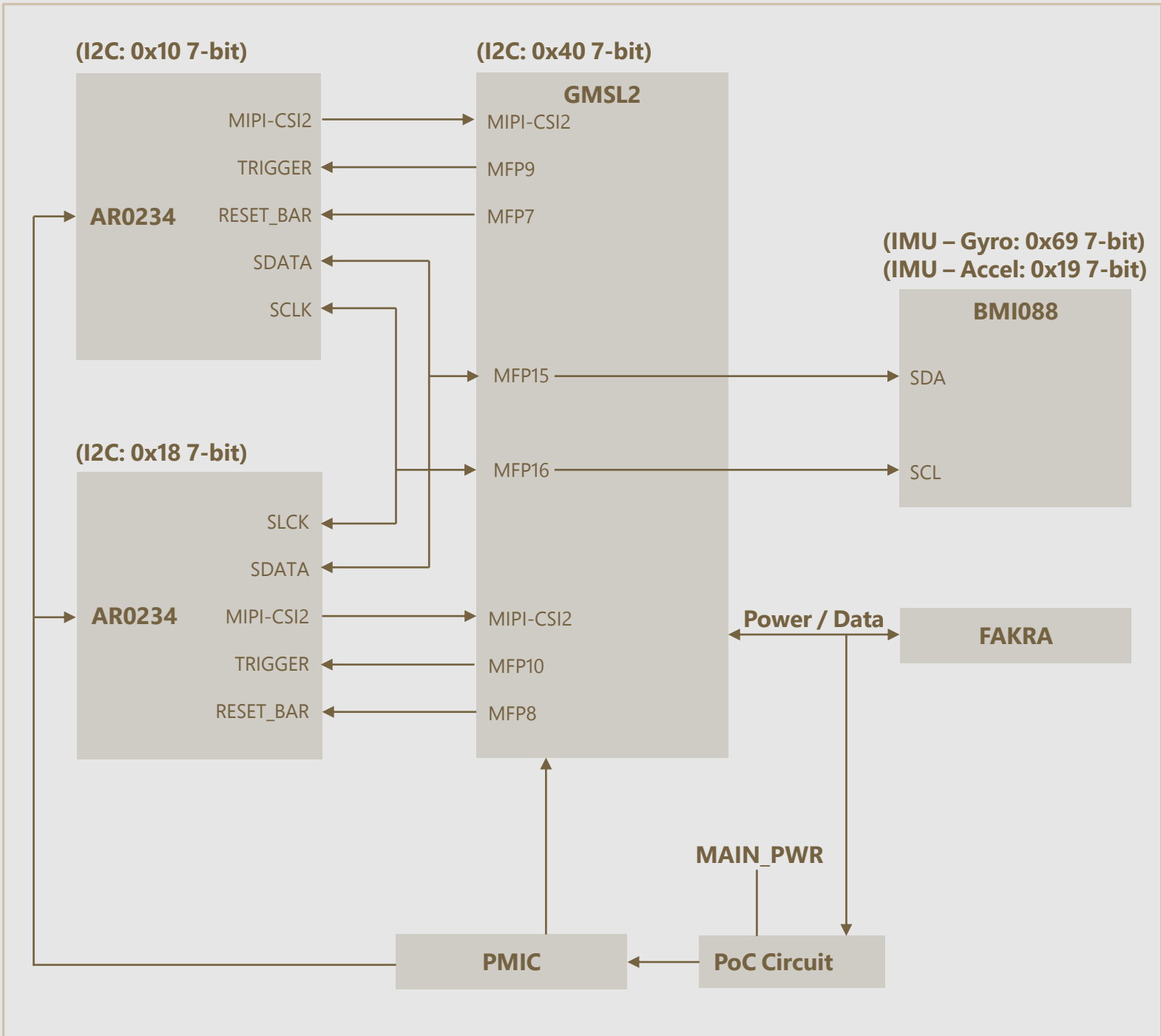
For more info, refer to:
<https://leopardimaging.com/product/accessories/adapters-carrier-boards/for-nvidia-jetson/e3653-a03/>



Connector to
 NVIDIA®
 Jetson AGX
 Xavier™ and
 AGX Orin™
 Developer Kit



SYSTEM BLOCK DIAGRAM

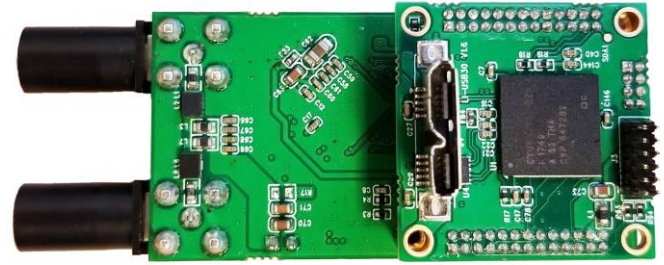


USB3.0 CAMERA KIT

LI-GMSL2-USB



Top View



Bottom View

LI-AR0234CS-STEREO-GMSL2-30 can connect to LI-GMSL2-USB as a USB 3.0 camera.

Part#: **LI-USB30-AR0234CS-STEREO-GMSL2-30**

SPECIFICATIONS

- USB 3.0 Super Speed support
- UVC compliant
- Global shutter
- Allows customization
- 12 VDC power supply for camera
- Weight: ~ 299 g
- Single Coax Cable transmits up to 12 meters PoC (Power over Cable)
- Power consumption: 86 mA @ 12 VDC
- Resolution: 2 * (1920 × 1200) @ 7.9 fps
- Compatible with Windows, Linux OS and other OS which have UVC drivers

NOTE: LI-USB30-AR0234CS-STEREO-GMSL2-30 syncs RAW images output side by side (no depth processing function)



BOM

| # | Items | QTY |
|---|-----------------------------|-----|
| 1 | LI-AR0234CS-STEREO-GMSL2-30 | 1 |
| 2 | LI-GMSL2-USB | 1 |
| 3 | 3-Meter Fakra Cable | 1 |
| 4 | 12 VDC Power Supply | 1 |
| 5 | USB3.0 Cable | 1 |

SDK SUPPORTED

- Camera Tool Source Code in C#
- Capture & Display
- Register Access Function

● REVISION HISTORY

| Revision | Description | Release Date |
|----------|--|--------------|
| 1.0 | First release. | 08 Sep 2022 |
| 1.1 | Updated power consumption. | 21 Nov 2022 |
| 1.2 | Added the following note on the USB30 page: LI-USB30-AR0234CS-STEREO-GMSL2-30 syncs RAW images output side by side (no depth processing function) | 26 Apr 2023 |
| 1.3 | 1. Added section "Recommended Adapter Boards". 2. Replaced block diagram with Pinout Connections. | 10 Oct 2023 |
| 1.4 | Added "Certification" section. | 26 Oct 2023 |
| 1.5 | 1. Updated introduction. 2. Added Features & Highlights section and Mounting Mechanism description. 3. Updated Technical Specifications, System Block Diagram and Image Orientation. | 26 Feb 2024 |
| 1.6 | Updated 2D dimensions. | 09 Apr 2024 |
| 1.7 | Updated 2D dimensions. | 17 Jul 2024 |

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