

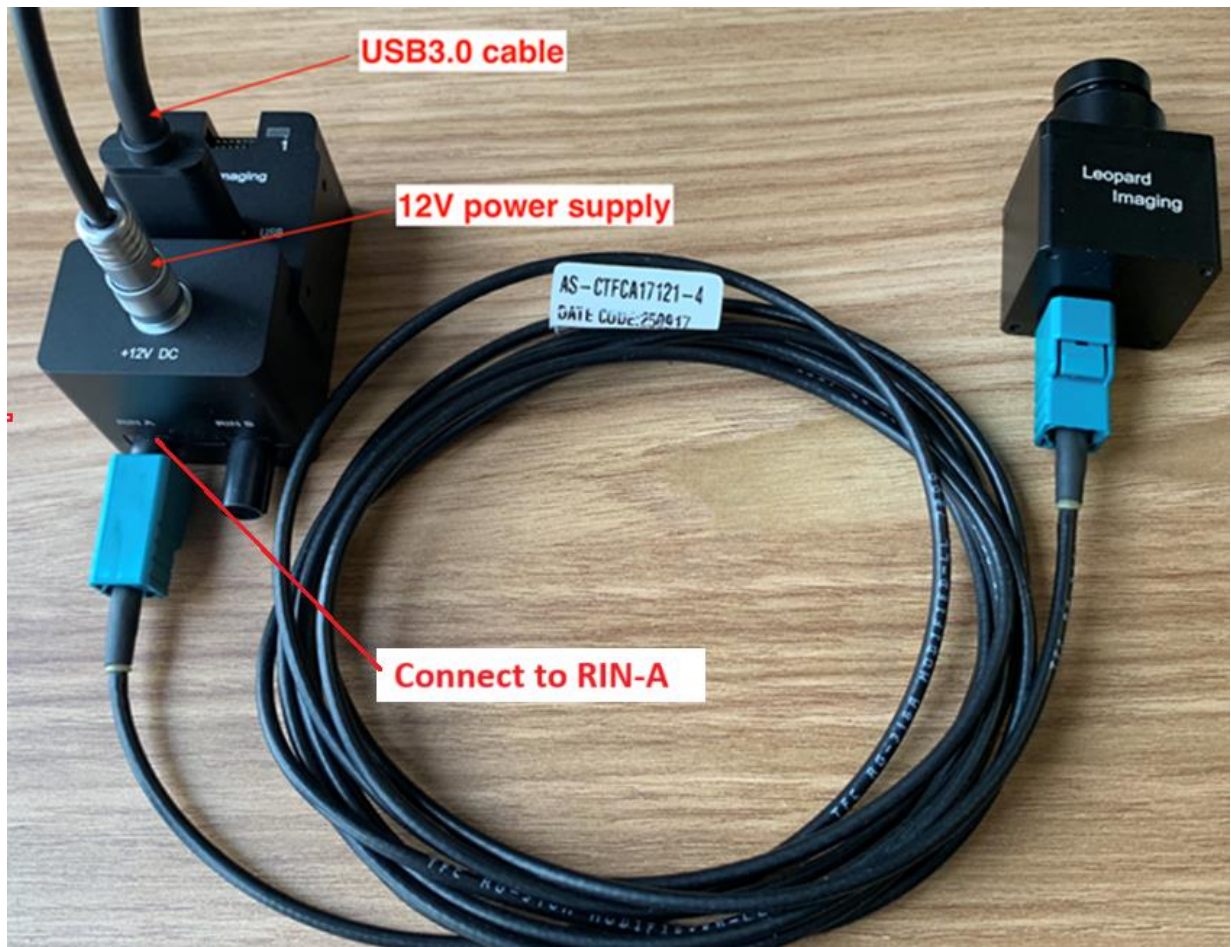


\* Copyright (c) 2024, Leopard Imaging Inc. All Rights Reserved.

### Overview

This firmware is for LI-USB30-IMX490-NVP2670-GMSL2 camera.  
This firmware supports 2848 x 1772 @ 30 fps.  
This camera includes Nextchip NVP2670 ISP and outputs YUV422 8-bit data.

Platform	Camera
1 x LI-GMSL2-FP-USB-BOX	1 x LI-IMX490-NVP2670
Cable	Adapter/Carrier Board
1 x USB 3.0 Micro-B cable 1 x FAK-SMZSMZ Fakra cable	1 x 12VDC power supply





LI-USB30-IMX490-NVP2670-GMSL2\_Firmware\_Release\_Note\_20240510

Revision	SVN version	Release Date	Author	Tested By
2024_05_10		05/10/2024		Shelby Hache
Updates				
Revision	Description			Release Date
2024_05_10	First Release			05/10/2024
Known bugs				



## Setup Procedure 1/3

### - Hardware:

1. LI-IMX490-NVP2670 x 1
2. LI-GMSL2-FP-USB-BOX Tester x 1
3. FAK-SMZSMZ Fakra Cable x 1
4. USB 3.0 Micro-B cable x 1
5. LI-PS12-01 x 1

### - Hardware Setup:

Connect the camera and USB 3.0 Tester board as the picture on the first page.

### - Software:

This camera kit can be tested with any one of the below software:

#### 1. Camera tool (Windows OS)

The Camera tool can be downloaded from the link below:

[https://www.dropbox.com/s/8daqfypyhnbj5/CameraUSB30\\_3\\_2\\_20190622.7z?dl=0](https://www.dropbox.com/s/8daqfypyhnbj5/CameraUSB30_3_2_20190622.7z?dl=0)

It's better to use the 7-zip to uncompress the package:

<http://www.7-zip.org/download.html>

And install the software below on your PC:

[https://www.dropbox.com/s/6usw140z8rqh2et/vcredist\\_x86.exe?dl=0](https://www.dropbox.com/s/6usw140z8rqh2et/vcredist_x86.exe?dl=0)

If needed, you can also download the camera tool SDK:

[https://www.dropbox.com/s/j6ccl8cvt75gu2g/USB30\\_CameraTool\\_SDK\\_rev1440\\_20190622.7z?dl=0](https://www.dropbox.com/s/j6ccl8cvt75gu2g/USB30_CameraTool_SDK_rev1440_20190622.7z?dl=0)

#### 2. Linux Camera tool (Linux OS)

The Linux camera tool can be downloaded from link below.

[https://www.dropbox.com/s/4m2efo696px9739/linux\\_camera\\_tool-master\\_20190624.zip?dl=0](https://www.dropbox.com/s/4m2efo696px9739/linux_camera_tool-master_20190624.zip?dl=0)

For how to install it, please refer to the README.md in below link. (the latest version of Linux camera tool may have an issue, so please use above Linux camera tool)

[https://github.com/LI01/linux\\_camera\\_tool](https://github.com/LI01/linux_camera_tool)

Please follow the README.md in GitHub to install the Linux camera tool.

There are instructions online for how to install the OpenCV on Ubuntu OS.

Below is an example:

<https://www.learnopencv.com/install-opencv-3-4-4-on-ubuntu-18-04/>

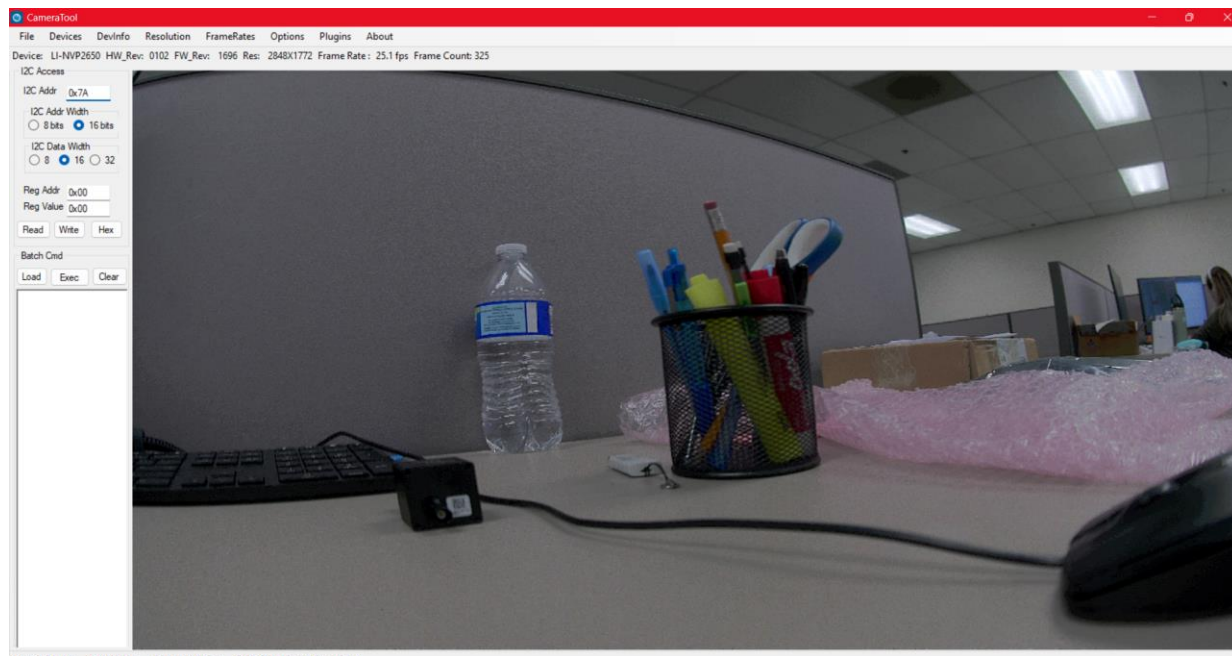


## Run Camera 1/3

### - Camera Tool (Windows OS)

1. Connect the camera to port RIN-A of USB 3.0 Tester. (refer to picture in page 1)
2. Plug in the 12V power supply to USB 3.0 Tester.
3. Connect the camera to your PC (**USB3.0 port**) using the USB 3.0 cable.
4. Open camera Tool.

Please make sure to complete these steps in numerical order. Steps 2 and 3 cannot be reversed.



### Color Matrix Function (NOT SUPPORTED):

This camera doesn't support the configuration of the color matrix.

### Register Access Function (NOT SUPPORTED):

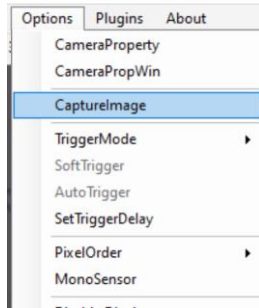
This camera doesn't support the register action function. It will include a pre-loaded ISP binary which will control the camera automatically.



## Run Camera 2/3

### Capture Image:

The images can be captured by clicking Options → CaptureImage. Two images (RAW and BMP) will be saved.



For raw image, it's YUV data encapsulated in RAW format.

This camera cannot output raw data.

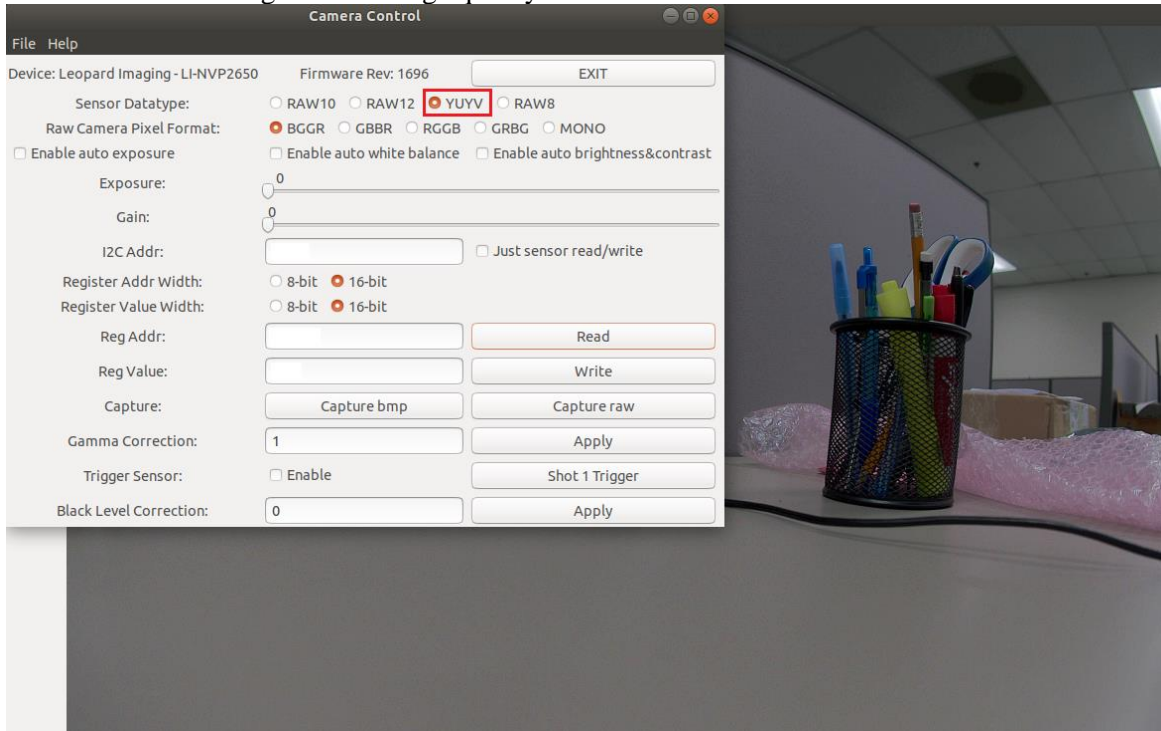


## Run Camera 3/3

### - Camera Tool (Linux OS)

1. Connect the camera to port RIN-A of USB 3.0 Tester. (refer to picture in page 1)
2. Connect the camera to PC (**USB3.0 port**) through USB 3.0 cable.
3. Open a terminal and use the command “leopard\_cam” to open the camera.

Set the camera as below to get better image quality.



Note: This camera includes ISP and output YUYV, the image quality should be good without changing any settings.





Note 1/3

This camera kit is pre-loaded with Firmware (in USB 3.0 Tester) and FPGA (in USB 3.0 Tester). If there is any new firmware from Leopard Imaging, you can refer to the instructions below to update them.

**1. Firmware Update:**

Please use the **LP\_USB3\_FirmwareUpdateTool** in the camera tool folder to update the firmware.

- 1) Click “Erase” to erase the old firmware.
- 2) Click “FW Update” button to select the lif file. (If the “FW\_Update is unavailable, please install the WestBridge driver, check below)
- 3) The update process may take about 15 seconds.
- 4) If the process takes too long, please disconnect the USB and reconnect it to PC.  
Then try the update tool again.

——Install WestBridge:

If the camera cannot be recognized after you update the firmware, and there is a device name “WestBridge” on the Device Manager, please download the driver from the link below and install it.

[https://www.dropbox.com/s/4yx2p31b7qo2gjx/WestBridge\\_driver.zip?dl=0](https://www.dropbox.com/s/4yx2p31b7qo2gjx/WestBridge_driver.zip?dl=0)

- 1) Right click on “WestBridge” and select Update Driver Software.
- 2) Choose browse my computer for driver software.
- 3) Click Browse, locate the driver at the downloaded and unzipped folder. (C:\temp\driver\bin\ for example)  
If your PC has Win7 or later version, please select the folder “win7”.
- 4) Click next and complete the installation process.

After install the driver, please update the firmware again.



Note 2/3

**2. FPGA Update:**

FPGA Binary: Radar\_USB3\_top\_top\_Radar\_USB3\_top\_top.rbt

1) Download the Lattice programmer tool software **Programmer Standalone 3.10 64-bit for Windows** from link below and install it to your PC.

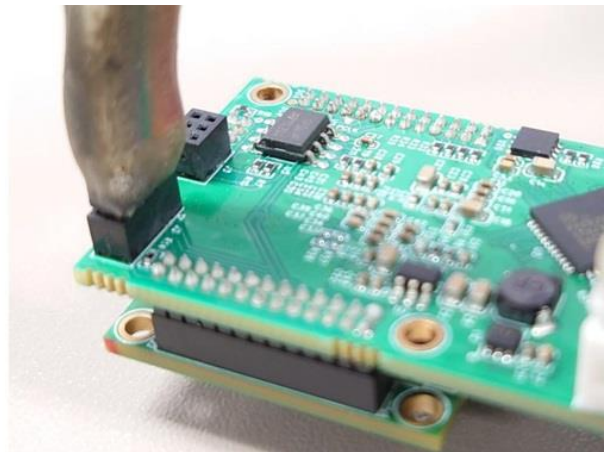
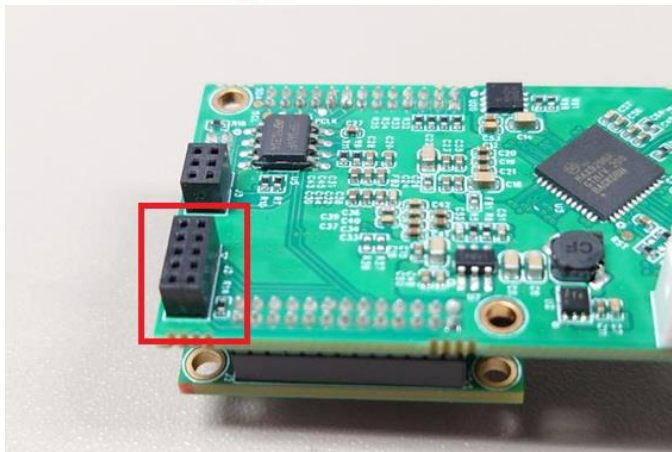
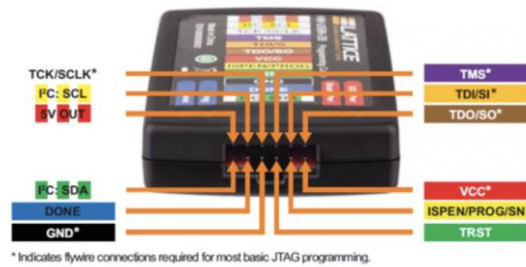
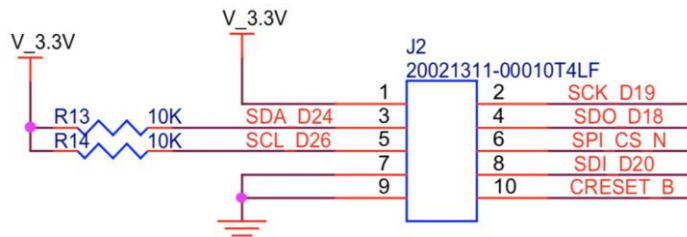
<http://www.latticesemi.com/programmer>

2) Connect the HW-USBN-2A or HW-USBN-2B to J2 of LI-MAX9296-DESER board. Below is the pinout. You may need to build an adapter cable for the programmer tool and J2. J2 is a 1.27mm pitch interface.

Below pins in red need to be connected.

Only below pins in red need to be connected:

TI954 Board ← → HW-USBN-2B	TI954 Board ← → HW-USBN-2B
Pin1: V_3.3V ← → VCC	Pin2: SCK_D19 ← → TCK/SCLK
Pin3: N/A	Pin4: SDO_D18 ← → TDO/SO
Pin5: N/A	Pin6: SPI_CS_N ← → ISPEN/PROG
Pin7: GND ← → GND	Pin8: SDI_D20 ← → TDI/SI
Pin9: N/A	Pin10: CRESET_B ← → TRST

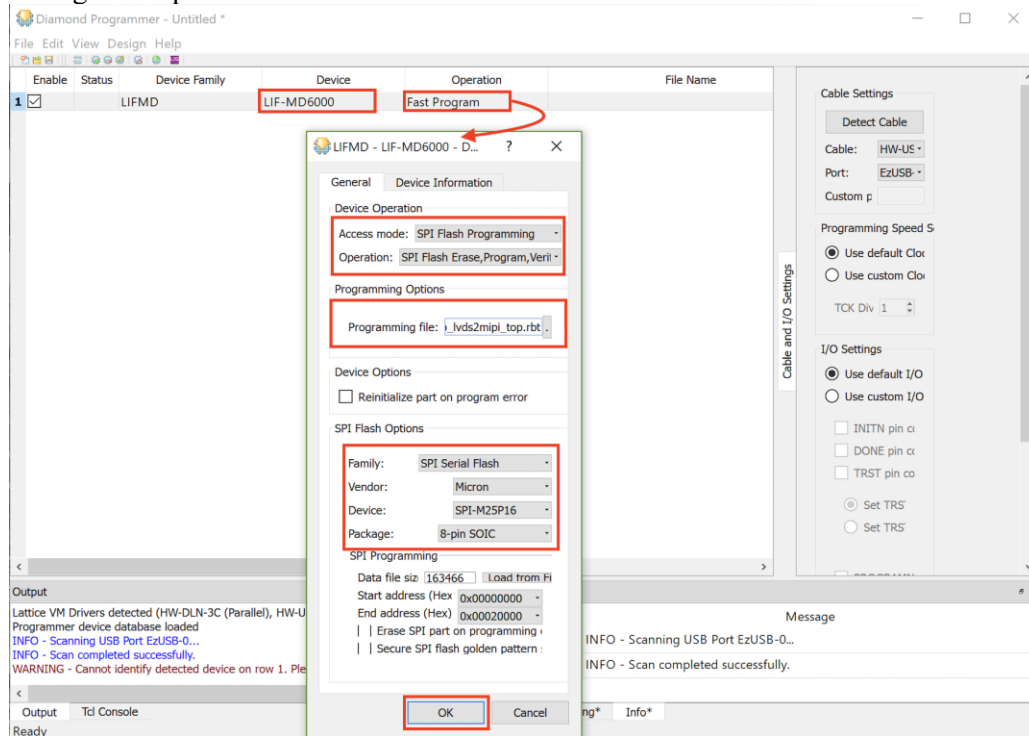






Note 3/3

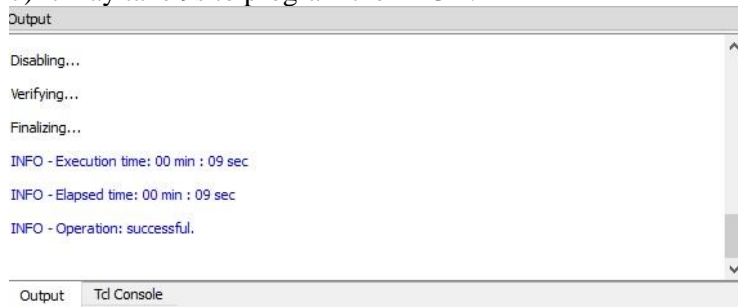
- 3) Connect the USB3.0 Tester to your PC via USB 3.0 cable.
- 4) Open **LP\_USB3\_FirmwareUpdateTool** in the camera tool folder and click “Erase” to erase the firmware.
- 5) Open Lattice software (which you installed in 1). The Device name should be “LIF-MD6000”. Set the settings of “Operation” as below and click “OK”.



- 6) Click program icon.



- 7) It may take 9s to program the FPGA.



- 8) Refer to the “Firmware Update” section to install the firmware.