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# Overview

This firmware is for LI-USB30-IMX390-GW5400-FPDLINKIII camera. This firmware supports 1920 x 1080 @ 60 fps.

This camera includes ISP and outputs YUV data without compression.

Platform	Camera
1 x LI-FPDLINKIII-FP-USB-BOX	1 x LI-IMX390-GW5400-FPDLINKIII
Cable	Adapter/Carrier Board
1 x USB 3.0 Micro-B cable 1 x FAK-SMZSMZ Fakra cable	1 x 12VDC power supply





Revision	SVN version	Release Date	Author	Tested By
2024_05_02		05/02/2024		Shelby Hache
Updates				
Revision		Description		Release Date
2024_05_02	First Release			05/02/2024
Known bugs				



## Setup Procedure 1/3

#### - Hardware:

- 1. LI-IMX390-GW5400-FPDLINKIII x 1
- 2. LI-FPDLINKIII-FP-USB-BOX x 1
- 3. FAK-SMZSMZ Fakra cable x 1
- 4. USB 3.0 Micro-B cable x 1
- 5. LI-PS12-01 x 1

#### - Hardware Setup:

Connect the camera and USB 3.0 Tester board as the picture on the first page.

#### - Software:

This camera kit can be tested with any one of the below software:

#### 1. Camera tool (Windows OS)

The Camera tool can be downloaded from the link below: https://www.dropbox.com/s/8daqfypyhnubjr5/CameraUSB30\_3\_2\_20190622.7z?dl=0

It's better to use the 7-zip to uncompress the package: <u>http://www.7-zip.org/download.html</u>

And install the software below on your PC: https://www.dropbox.com/s/6uswl40z8rqh2et/vcredist\_x86.exe?dl=0

If needed, you can also download the camera tool SDK: https://www.dropbox.com/s/j6ccl8cvt75gu2g/USB30 CameraTool SDK rev1440 20190622.7z?dl=0

Note: Since this is a YUV camera, you can also use AMcap or other regular software on Windows OS.

#### 2. Linux Camera tool (Linux OS)

The Linux camera tool can be downloaded from link below. https://www.dropbox.com/s/4m2efo696px9739/linux\_camera\_tool-master\_20190624.zip?dl=0

For how to install it, please refer to the README.md in below link. (the latest version of Linux camera tool may have an issue, so please use above Linux camera tool) https://github.com/LI01/linux\_camera\_tool

Please follow the README.md in GitHub to install the Linux camera tool. There are instructions online for how to install the OpenCV on Ubuntu OS. Below is an example:

https://www.learnopencv.com/install-opencv-3-4-4-on-ubuntu-18-04/

Note: Since this is a YUV camera, you can also use guvcview or other regular software on Linux OS.

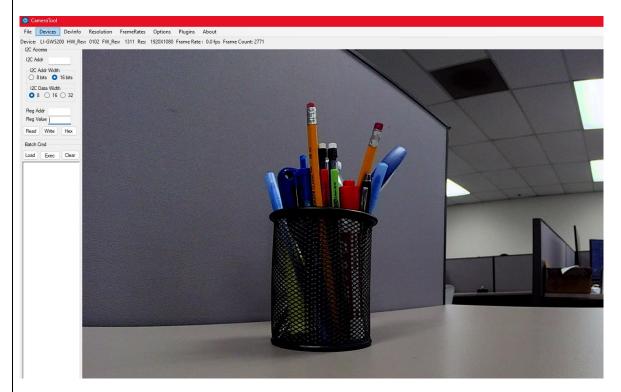


# Run Camera 1/3

### - Camera Tool (Windows OS)

- 1. Connect the camera to port RIN-A of USB 3.0 Tester. (refer to picture in page 1)
- 2. Plug in the 12V power supply to USB 3.0 Tester.
- 3. Connect the camera to your PC (USB3.0 port) using the USB 3.0 cable.
- 4. Open camera Tool.

Please make sure to complete these steps in numerical order. Steps 2 and 3 cannot be reversed.



Color Matrix Function (NOT SUPPORTED): This camera doesn't support the configuration of the color matrix.

Register Access Function (NOT SUPPORTED):

This camera doesn't support the register action function. It will include a pre-loaded ISP binary which will control the camera automatically.



## Run Camera 2/3

Capture Image:

The images can be captured by clicking Options  $\rightarrow$  CaptureImage. Two images (RAW and BMP) will be saved to PC.

Options	Plugins	About	
Cam	eraPropert	y	
Cam	eraPropWi	n	
Capt	urelmage		
Trigg	JerMode		•
Soft	SoftTrigger		
Auto	Trigger		
SetTr	riggerDelay		
PixelOrder		•	
Mon	MonoSensor		

For raw image, it's actually YUV data encapsulated in RAW format. This camera cannot output raw data.



# Run Camera 3/3

#### - Camera Tool (Linux OS)

- 1. Connect the camera to port RIN-A of USB 3.0 Tester. (refer to picture in page 1)
- 2. Plug in the 12V power supply to USB 3.0 Tester.
- 3. Connect the camera to PC (USB3.0 port) through USB 3.0 cable.
- 4. Open a terminal and use the command "leopard\_cam" to open the camera.

Please make sure to complete these steps in numerical order. Steps 2 and 3 cannot be reversed.

Set the camera as below to get better image quality.

File Help Device: Leopard Imaging - LI-IMX390	Firmware Rev: 1311	EXIT		1
	○ RAW10 ○ RAW12 ○ YU		THE A	
	O BGGR O GBBR O RGGB			
		Enable auto brightness&contrast		tt
Exposure:	0			
Gain:	۹			)
I2C Addr:	0x	Just sensor read/write		
Register Addr Width:	<b>○</b> 8-bit ○ 16-bit			
Register Value Width:	🗿 8-bit 🔿 16-bit			Cox.
Reg Addr:	0x	Read		2.20
Reg Value:	Ox	Write		2
Capture:	Capture bmp	Capture raw		
Gamma Correction:	1	Apply		
Trigger Sensor:	Enable	Shot 1 Trigger		
Black Level Correction:	0	Apply		

settings.



# Note 1/3

This camera kit is pre-loaded with Firmware (in USB 3.0 Tester) and FPGA (in USB 3.0 Tester). If there are any new firmware and/or FPGA binary from Leopard Imaging, you can refer to below instructions to update them.

## 1. Firmware Update:

Please use the LP\_USB3\_FirmwareUpdateTool in the camera tool folder to update the firmware.

1) Click "Erase" to erase the old firmware.

2) Click "FW Update" button to select the lif file. (If the "FW\_Update is unavailable, please install the WestBridge driver, check below)

3) The update process may take about 15 seconds.

4) If the process takes too long, please disconnect the USB and reconnect it to PC. Then try the update tool again.

-----Install WestBridge:

If the camera cannot be recognized after you update the firmware, and there is a device name "WestBridge" on the Device Manager, please download the driver from the link below and install it.

https://www.dropbox.com/s/4yx2p31b7qo2gjx/WestBridge\_driver.zip?dl=0

1) Right click on "WestBridge" and select Update Driver Software.

2) Choose "browse my computer" for driver software.

3) Click Browse, locate the driver at the downloaded and unzipped folder. (C:\temp\driver\bin\ for example)

If your PC has Win7 or later version, please select the folder "win7".

4) Click next and complete the installation process.

After install the driver, please update the firmware again.



Note 2/3

# 2. FPGA Update:

FPGA Binary: Radar\_USB3\_top\_top\_Radar\_USB3\_top\_top.rbt

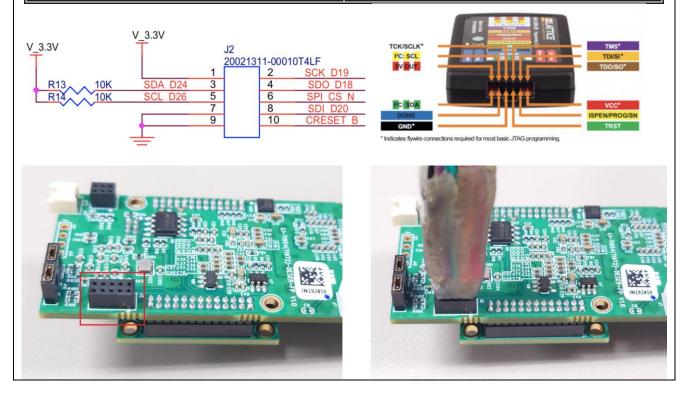
1) Download the Lattice programmer tool software **Programmer Standalone 3.10 64-bit for Windows** from link below and install it to your PC.

http://www.latticesemi.com/programmer

2) Connect the HW-USBN-2A or HW-USBN-2B to J2 of LI-TI954-DESER board. Below is the pinout. You may need to build an adapter cable for the programmer tool and J2. J2 is a 1.27mm pitch interface. Below pins in red need to be connected.

Only below pins in red need to be connected:

TI954 Board <> HW-USBN-2B	TI954 Board <> HW-USBN-2B
Pin1: V_3.3V <> VCC	Pin2: SCK_D19 <> TCK/SCLK
Pin3: N/A	Pin4: SDO_D18 <> TDO/SO
Pin5: N/A	Pin6: SPI_CS_N <> ISPEN/PROG
Pin7: GND <> GND	Pin8: SDI_D20 <> TDI/SI
Pin9: N/A	Pin10: CRESET_B <> TRST





#### Note 3/3 3) Connect the USB3.0 Tester to your PC via USB 3.0 cable. 4) Open LP\_USB3\_FirmwareUpdateTool in the camera tool folder and click "Erase" to erase the firmware. 5) Open Lattice software (which you installed in 1). The Device name should be "LIF-MD6000". Set the settings of "Operation" as below and click "OK". 🔕 Di d Programmer - Untitl File Edit View Design Help Enable Status Device Family Device Operation File Name Cable Settings 1 🗹 LIFMD LIF-MD6000 Fast Program Detect Cable 😂 LIFMD - LIF-MD6000 - 🗖.. × Cable: HW-US · EzUSB- \* Port: General Device Information Custom p Device Operation Programming Speed S Access mode: SPI Flash Programming Use default Cloc Operation: SPI Flash Erase, Program, Veril O Use custom Clor Programming Options TCK Div 1 🗘 9 Programming file: <a>[vds2mipi\_top.rbt</a>. pue I/O Settings Cable Device Options Use default I/O Reinitialize part on program error O Use custom I/O SPI Flash Options INITN pin co DONE pin co Family: SPI Serial Flash TRST pin co Vendor: Micron Set TRS' Device: SPI-M25P16 -O Set TRS Package: 8-pin SOIC SPI Programming Data file siz 163466 Load from Fi Start address (Hex) 0x00000000 -End address (Hex) 0x00020000 -| Erase SPI part on programming Output Lattice VM Drivers detected (HW-DLN-3C (Parallel), HW-U Programmer device database loaded INFO - Scaning USB Port EXUSB-0... INFO - Scan completed successfully. Message INFO - Scanning USB Port EzUSB-0... | | Secure SPI flash golden pattern INFO - Scan completed successfully WARNING - Cannot identify detected device on row 1. Ple < Tcl Console Output OK Cancel ng\* Info\* Ready 6) Click program icon. Diamond Programmer - Untitled \* File Edit View Design Help \* \* - \* \* \* \* \* \* \* \* Device Family Enable Status 7) It may take 9s to program the FPGA. Output Disabling... Verifying... Finalizing... INFO - Execution time: 00 min : 09 sec INFO - Elapsed time: 00 min : 09 sec INFO - Operation: successful. Output Tcl Console 8) Refer to the "Firmware Update" section to install the firmware.